

APPENDIX

Table 1. J1 Definition, Thermistors & Personality Pins

Connector	Pin	Mode	Type / Load	Function
J1	1	Input	Analog 0-5V	Thermistor Input
				[FF1]
J1	2	Input	Analog 0-5V	Thermistor Input
				[FF2]
J1	3	Input	Analog 0-5V	Thermistor Input
				[FZ]
J1	4	Input	Analog 0-5V	Thermistor Input
			·	[EVAP]
J1	5	Input	Analog 0-5V	Thermistor Input
				[Pan]
J1	6	Input	Digital 0-5V	Personality Input
J1	7	Input	Digital 0-5V	Personality Input
J1	8	Output	5V Power Supply	Reference for
		_		Thermistors
J1	9	NC	NC	NC

Connector	Pin	Mode	Type / Load	Function
J2	1	Input	Digital 0-12V	RPM Input
		_		[Evap]
J2	2	Input	Digital 0-12V	RPM Input
		_		[Cond]
J2	3	Power	Digital 0V – Hi Z	Motor Common
			/ 850 mA	[Evap & Cond]
J2	4	Output	Analog 0-12V /	Fan Drive
		_	425 mA	Voltage [Evap]
J2	5	Output	Analog 0-12V /	Fan Drive
		_	425 mA	Voltage [Cond]
J2	6	Output	Digital 0V – Hi Z	Low Active Fan
		_	/ 200 mA	Output [FF]
J2	7	Output	Digital 0V – Hi Z	Low Active Fan
			/ 200 mA	Output [Pan]
J2	8	Power	12V Power	Power For Low
			supply / 400 mA	Active Fans [FF
				& Pan]

Table 3. J3 Definition, Encoders and Mullion Damper

Connector	Pin	Mode	Type / Load	Function
J3	1	Output	Digital 0-12V / 60 mA	Stepper Motor Coil (normally opposite polarity of pin 2)

Connector	Pin	Mode	Type / Load	Function
J3	2	Output	Digital 0-12V / 60	Stepper Motor
			mA	Coil (normally
				opposite polarity
				of pin 1)
J3	3	Output	Digital 0-12V / 60	Stepper Motor
			mA	Coil (normally
				opposite polarity
				of pin 4)
J3	4	Output	Digital 0-12V / 60	Stepper Motor
			mA	Coil (normally
				opposite polarity
				of pin 3)
J3	5	Input	Digital 0-5V	Encoder Drive
	'			[FF]
J3	6	Input	Digital 0-5V	Encoder Drive
			_	[FZ]
J3	7	Output	Digital 0-5V	Encoder Input
				[Bit 3]
J3	8	Output	Digital 0-5V	Encoder Input
				[Bit 2]
J3	9	Output	Digital 0-5V	Encoder Input
				[Bit 1]
J3	10	Output	Digital 0-5V	Encoder Input
				[Bit 0]

Table 4. J4 Definition, Communications

Connector	Pin	Mode	Type / Load	Function
J4	1	Input / Output	Digital 0-5V	Serial
				Communication
				Stream
J4	2	Output	12V Power	Power for
			supply / 1.25 A	Temperature
				Control and
				Dispenser
				Boards
J4	3	Output	DC Common /	DC Common
ĺ			1.25 A	(Not connected
				to earth ground)
J4	4	Input	Digital 0-12V	Dumb Dispenser
				Status Input
J4	5	Input	Digital 0-12V	Dumb Dispenser
				Status Input

Table 5. J5 Definition, Pan Damper Control

Connector	Pin	Mode	Type / Load	Function
J5	1	Output	Digital 0-12V /	Damper Drive
			300 mA	Opposite of Pin 2
J5	2	Output	Digital 0-12V /	Damper Drive
			300 mA	Opposite of Pin 1
J5	3	Output	Digital 0-12V /	Damper Drive
			300 mA	Opposite of Pin 4
J5	4	Output	Digital 0-12V /	Damper Drive
			300 mA	Opposite of Pin 3

Table 6. J6 Definition, Flash Programming

Table 6. Jo Definition, Flash Programming					
Connector	Pin	Mode	Type	Function	
J6	1	Output	5 Volt Power	Power Supply	
			Supply	Output	
J6	2	Output	DC Common	DC Common	
				(Not connected	
				to earth ground)	
J6	3	Input	Digital 0-5V	Serial Data	
				Received	
J6	4	Output	Digital 0-5V	Serial Data	
				Transmitted	
J6	5	NC	NC	NC	
J6	6	NC	NC	NC	
J6	7	Input	12 Volt Power	VFPP	
		•	Input		
J6	8	Input	Digital 0-5V	Test Pin	
J6	9	Input	Digital 0-5V	P19	
J6	10	Input	Digital 0-5V	Reset	
J6	11	NC	NC	NC	
J6	12	NC	NC	NC	
J6	13	Output	DC Common	DC Common	
				(Not connected	
				to earth ground)	
J6	14	Input	DC Common	DC Common	
		_		Select	
				Programming	
				Mode	

Table 7. J7 Definition, AC Loads

Connector	Pin	Mode	Type / Load	Function
J7	1	Output	117VAC Line / 4 A	Auger Drive Relay Connects to Pin 4 of This Connector

Connector	Pin	Mode	Type / Load	Function
J7	2	Output	117VAC Line /	Crusher Drive
			0.3 A	
J7	3	Output	117VAC Line /	Water Valve
			0.5 A	Drive
J7	4	Input	117VAC Line /	Auger Drive
			4.3 A	Relay Connects
				to Pin 1 of This
				Connector
J7	5	Output	117VAC Line /	Thaw Heater
			200 mA	Power
J7	6	Input	117VAC Line	Fresh Food Door
J7	7	Input	117VAC Line	Freezer Door
J7	8	NC	NC	NC
J7	9	Input	117VAC Neutral	Return for Door
:				Detection
				Circuits

Table 8. J8 Definition, Compressor Run

Connector	Pin	Mode	Type / Load	Function
Ј8	1	Output	117VAC Line / 3	Compressor Run
			A	Relay

Table 9. J9 Definition, Defrost

Connector	Pin	Mode	Type / Load	Function
J9	1	Output	117VAC Line /	Defrost Run
			6.4 A	Relay

Table 10. J11 Definition, Line Input

Connector	Pin	Mode	Type	Function
J11	1	Input	117VAC Line	Line Input

Table 11. J12 Definition, Pan Heater

Connector	Pin	Mode	Type	Function
J12	1	Output	117VAC Line /	Pan Heater
			0.5 A	Relay Output

Table 12. Set Points Associated With Various LEDs

PLATFORM	Leap	Frog	B	PO	Quantum	
LED	Fresh	Freezer	Fresh	Freezer	Fresh	Freezer
	Food	(Degrees	Food	(Degrees	Food	(Degrees
	(Degrees	F)	(Degrees	F)	(Degrees F)	F)
	F)		F)			
0	Off	Off	Off	Off	Off	Off
1 – Warmest	45	6	46	6	45	6
2	40	4	41	4	40	4
3	39	3	39	3	39	3
4	38	1	38	1	38	1
5	37	0	37	0	37	0
6	36	-1	36	-1	36	-1
7	35	-3	35	-1	35	-3
8	35	-4	35	-4	35	-4
9 – Coldest	34	-6	34	-6	34	-6

Table 13. Diagnostic Key Sequences

FZ	FF	Mode	Comments
Display	Display		
0	1	HMI to Main Control Communications	The Turbo Cool LED will light up confirming communication between the two boards.
0	2	HMI to Dispenser Communications	The Turbo Cool LED will light up confirming communication between the two boards.
0	3	Dispenser to Main Control Communications	The Turbo Cool LED will light up confirming communication between the two boards.
0	4	Encoder Test	As the encoders are rotated, the test mode will stop flashing and the corresponding setting of the encoder will appear on the freezer display of the HMI.
0	5	HMI Self Test	See below.
0	6	Control and Sensor System Self Test	See below.
0	7	Open Duct Door	Duct Door will open for 10 seconds and then close.
0	8	Sweat Heater Test	Turn the sweat heater on for 60 seconds.
0	9	Open Dampers	Each Damper will open, pause briefly, and then close.

FZ	FF	Mode	Comments
Display	Display		
1	0	Fan Speed Test	Each fan will run for 30 seconds at low speed, then for 30 seconds at medium speed, and finally for 30 seconds at high speed.
1	1	100% Run Time	This mode runs the sealed system 100% of the time. This will automatically time out after 1 hour of run time.
1	2	Enter Prechill	This places the freezer in prechill mode. It will return to normal operation on its own.
1	3	Enter Defrost	This will set the refrigerator into defrost mode. It will return to normal operation on its own. If the cavity is not cold when this mode is executed, it may execute extremely fast.
1	4	Refrig	Causes a system reset.
1	5	Test Mode Exit	Causes a temperature board reset

Table 14.

Davisa	Detection	Stratomy
<u>Device</u>	<u>Detection</u>	Strategy
FZ Thermistor	FZ Thermistor Circuit	 Set FZ unfiltered temp =-40
	OPEN	ensuring unigrid bottom row
		(X,W,V,U,T,S) execution.
		EFOSSO disabled.
FF1 or FF2	FFx Thermistor Circuit	• Quantum only – Disregard out of
Thermistor	OPEN	range FFx temp. in the FF avg.
(Quantum)		temp. calculation
FF1 and FF2	FF1 Thermistor Circuit	 Set FF no freeze < FF avg.
Thermistor (or	OPEN, AND	unfiltered temp < FF low
BPO, Leap single	FF2 Thermistor Circuit	hysteresis, ensuring unigrid
FF thermistor)	OPEN	(E,K,Q,W) column execution
Damper Operation	 Damper commanded open, 	Send appropriate command again
	but FF avg temperature	to damper (open/close)
	increases > 0.3F in 5 min.	
	Damper commanded	
	closed, but FF avg	
	temperature decreases > 0.3F	
	in 5 min.	
Evap. Thermistor	Evap. Thermistor Circuit	Defrost operation occurs as
	OPEN	follows: defrost duration of 20
		minutes, dwell duration of 5
		minutes, and 8 hours of
		compressor run time elapses
		between defrosts

<u>Device</u>	<u>Detection</u>	Strategy
Evap. Fan	No RPM feedback	Operate evaporator fan at 100% duty cycle.
Power Line Fault	• None	 Store defrost state and defrost timer status every 30 minutes or upon defrost state change. Algorithm uses saved state and timer values if FZ temp < Defrost termination temp. Algorithm reinitializes state and timer values if FZ temp > = Defrost termination temp.

Table 15. Control Board Commands

Address	Com. Byte	Command Received	Communication Response	Physical Response
0x10	0x01	Firmware Version	<3 byte ascii version>	
0x10	0x61	Monogram Pan Heater Control		On if Data = 0x51 and Off if Data = 0x41
0x10	0x62	Feature Pan Damper 1 Control		On if Data = 0x51 and Off if Data = 0x41
0x10	0x63	Feature Pan Damper 2 Control		On if Data = 0x51 and Off if Data = 0x41
0x10	0x64	Feature Pan Heater Control		On if Data = 0x51 and Off if Data = 0x41
0x10	. 0x65	Damper Control		Open if Data = 0x51 and Close if Data = 0x41
0x10	0x66	Start/Stop Condenser Fan		0x41=Off 0x51=On
0x10	0x67	Start/Stop Evaporator Fan (Variable Speed)		0x00=Off, 0x01=Low, 0x02=Med, 0x03=High

Address	Com. Byte	Command Received	Communication Response	Physical Response
0x10	0x68	Start/Stop Fresh Food Fan (Variable Speed)	·	0x00=Off, 0x01=Low, 0x02=High
0x10	0x69	Start/Stop Turbo Mode		Start If Data = 0x51 and Stop If Data = 0x41
0x10	0x6A	Start/Stop Feature Pan Fan (Variable Speed)		Chill Pan Fan Starts With Data Value Setting Speed
0x10	0x6B	Condenser Fan Speed Request	1 Bytes 0x51=On, 0x41=Off	
0x10	0x6C	Evaporator Fan Speed Request	2 Bytes For Logical: 0=Off 1=Low, 2=Med, 3=High	0x41=Logical State, 0x51=RPM
0x10	0x6D	Fresh Food Fan Speed Request	1 Byte 0=Off, 1=Low 2=High	•
0x10	0x6E	Feature Pan Fan Speed Request	1 Byte 0x51=On, 0x41=Off	
0x10	0x70	Dispense		One Data Byte with masks for each selection Water = 0x01 Cubed = 0x02 Crushed = 0x04
0x10	0x71	Engage Water Valve		Engage If Data = 0x51 and Release If Data = 0x41
0x10	0x72	Energize Defrost Heater		Energize If Data = 0x51 and Release If Data = 0x41
0x10	0x73	Energize Auger Motor		Energize If Data = 0x51 and Release If Data = 0x41

Address	Com. Byte	Command Received	Communication Response	Physical Response
0x10	0x74	Start Compressor		Start If Data = 0x51 and Stop If Data = 0x41
0x10	0x75	Energize Crusher Bypass Solenoid		Energize If Data = 0x51 and Release If Data = 0x41
0x10	0x76	Read Sealed System ON Time	2 Bytes <minutes of="" on="" time=""></minutes>	
0x10	0x77	Read Sealed System OFF Time	2 Bytes <minutes of="" off="" time=""></minutes>	
0x10	0x80	Read FF Thermistor 1	2 Bytes Temp X 100 or the A/D Counts	0x41 = Inst. Value 0x51 = Filtered 0x61 = Unamp. 0x71 = A/D Counts
0x10	0x81	Read FF Thermistor 2	2 Bytes Temp X 100 or the A/D Counts	0x41 = Inst. Value 0x51 = Filtered 0x61 = Unamp. 0x71 = A/D Counts
0x10	0x82	Read FZ Thermistor	2 Bytes Temp X 100 or the A/D Counts	0x41 = Inst. Value 0x51 = Filtered 0x61 = Unamp. 0x71 = A/D Counts
0x10	0x83	Read Evaporator Thermistor	2 Bytes Temp X 100 or the A/D Counts	0x41 = Inst. Value 0x51 = Filtered 0x61 = Unamp. 0x71 = A/D Counts
0x10	0x84	Read Feature Pan Thermistor	2 Bytes Temp X 100 or the A/D Counts	0x41 = Inst. Value 0x51 = Filtered 0x61 = Unamp. 0x71 = A/D Counts
0x10	0x85	Read Ambient Thermistor	2 Bytes Temp X 100 or the A/D Counts	0x41 = Inst. Value 0x51 = Filtered 0x71 = A/D Counts
0x10	0x86	Get Number of Door Openings	4 Bytes: FZ MSB, FZ LSB, FF MSB, FF LSB	

Address	Com. Byte	Command Received	Communication Response	Physical Response
0x10	0x87	Reset Door Openings Counter		
0x10	0x88	Read Sensors	<state of="" various<br="">Sensors -> 1 byte></state>	
0x10	0x89	Read Dispense Counters	6 Bytes: Water MSB, Water LSB, Cubed MSB, Cubed LSB, Crushed MSB, Crushed LSB	
0x10	0x8A	Enter Feature Pan Defrost Mode		0 = Off 1 = Small Pkg. 2 = Med. Pkg. 3 = Lg. Pkg.
0x10	0x8B	Enter Feature Pan Quick Chill Mode		0 = Off 1 = 15 min. 2 = 30 min. 3 = 45 min.
0x10	0x8C	Reset Dispense Counters		
0x10	0x90	Reset Freshness Filter Timer		
0x10	0x91	Reset Water Filter Timer		
0x10	0xA0	Set EEPROM Read Address		Memory pointer is set for next Diagnostic eeprom read sequence.
0x10	0xA1	Set EEPROM Read Length		Memory read length is set for next Diagnostic eeprom read sequence.
0x10	0xA2	Read EEPROM	<eeprom by="" commands="" data="" defined="" previous="" two=""></eeprom>	

Address	Com. Byte	Command Received	Communication Response	Physical Response
0x10	0xA3	Write EEPROM		First two data bytes define the eeprom address, bytes three and four are the data written to that 16 bit area.
0x10	0xA4	Read Set Points	<pre><set (first="" byte="" eeprom="" ff,="" from="" fz)="" is="" point="" second="" temperatures=""></set></pre>	
0x10	0xA5	Write Set Points		Send Set Points to EEPROM (First Byte is FF, Second Byte is FZ)
0x10	0xB0	Check Refrigerator Status	<state of<br="">Refrigerator></state>	
0x10	0xB1	Perform FF Fan Diagnostics	1 = Fan OK 2 = Fan Missing or Open 3 = Fan Shorted 4 = Fan Stalled	
0x10	0xB2	Perform Evap Fan Diagnostics	1 = Fan OK 2 = Fan Missing or Open 3 = Fan Shorted 4 = Fan Stalled 5 = Blade Missing	
0x10	0xB3	Perform Cond Fan Diagnostics	1 = Fan OK 2 = Fan Missing or Open 3 = Fan Shorted 4 = Fan Stalled	
0x10	0xB4	Perform Feature Fan Diagnostics	1 = Fan OK 2 = Fan Missing or Open 3 = Fan Shorted 4 = Fan Stalled	
0x10	0xB5	Status of Outputs	2 Bytes <status digital="" i="" o="" of=""></status>	

Address	Com. Byte	Command Received	Communication Response	Physical Response
0x10	0xBA	Get Encoder Settings	2 Bytes: FF Setting, FZ Setting	
0x10	0xBC	Get Model Inputs	1 Byte with value of model inputs	
0x10	0xC0	Enter Diagnostic Mode		All outputs are off or closed
0x10	0xC1	Exit Diagnostic Mode		Will reset refrigerator
0x10	0xF9	Forced Reset		
0x10	0xFA	Forced Prechill		
0x10	0xFB	Forced Defrost		
0x10	0xFC	100% Run		.
0x10	0xFD	Disable defrost		
0x10	0xFE	Calibrate thermistor channels against known resistence		

Bit 128	Bit 64	Bit 32	Bit 16	Bit 4	Bit 2	Bit 2	Bit 1
0	0	FF Door	FZ Door	0	0	0	0

Table 17

Byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	FF Door Sensor	FZ Door Sensr	Water Disp. Valve State	Auger State	State of Com- press	Crush Sol. State	Mongr. Heater	Defrst Heatr State
1	Damp. State	Feat. Pan Damp. 1 State	Feat. Pan Damp. 2 State	Feat. Pan Heatr.	Feat. Pan Fan	Cond Fan	FF Fan	0
2	FF1 Temp MSB							
3	FF1 Ter	mp LSB			-			
4	FF2 Te	mp MSB						
5	FF2 Te	mp LSB						
6	FF Ave	rage Tem	p MSB					
7	FF Ave	rage Tem	p LSB					
8	FZ Tem	p MSB						
9	FZ Tem	ip LSB					<u>.</u>	
10	Evap To	Evap Temp MSB						
11	Evap To	Evap Temp LSB						
12	Feature	Feature Pan Temp MSB						
13		Pan Tem						
14	Evap Fa	an Speed	(0=Off, 1)	=Low, 2=	=Med, 3=	High)		

Table 18

	Table	, ·		·
Address	Com.	Command	Communication	Physical Response
	Byte	Received	Response	
0x11	0x01	Firmware Version	<3 byte ascii	
			version>	
0x11	0x6F	EEPROM data		
		from		
		mainboard		
0x11	0x90	Set Display		See table below
0x11	0x91	Read Buttons	<state of="" td="" various<=""><td></td></state>	
			Buttons -> 4 bytes >	
0x11	0x92	Pulse Beeper		
0x11	0xA4	Reply from main		
		with temperature		
		settings		
0x11	0xBA	Reply from main		
		with encoder		
		settings		
0x11	0xC0	Door Open		0x51 = door open
	~			0x41 = door closed
0x11	0xF2	Temperature to		
		main/dispenser		
		communications		
		test		
0x11	0xF3	Dispenser to main		
		communications		
		test		
0x11	0xF4	Open duct door		
0x11	0xF5	Sweat heater test		
0x11	0xF6	Sensor system self-		
		test		
0x11	0xF9	Forced reset		

4.4	Table 19							
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	
Thaw	Cool	Lock	Filter	Door	Cube	Crush	Water	
1								
0 .	0	0	Chill	Chill	Chill	Thaw	Thaw	
		•	3	2	1	3	2	
Bits 0 -	Bits 0 – 6, Fresh Food LED 0							
Bits 0 -	- 6, Fresh	Food LI	ED 1	<u> </u>				
Bits 0 -	6, Fresh	Food LI	ED 2			_		
Bits 0 -	Bits 0 – 6, Freezer LED 0							
Bits 0 -	Bits 0 – 6, Freezer LED 1							
Bits 0 -	6, Freez	er LED 2	2					
	Bit 7 Thaw 1 0 Bits 0 -	Bit 7 Bit 6 Thaw Cool 1 0 0 Bits 0 - 6, Fresh Bits 0 - 6, Fresh Bits 0 - 6, Freez Bits 0 - 6, Freez Bits 0 - 6, Freez	Bit 7 Bit 6 Bit 5 Thaw Cool Lock 1 0 0 0 Bits 0 - 6, Fresh Food LI Bits 0 - 6, Freezer LED 0 Bits 0 - 6, Freezer LED	Bit 7 Bit 6 Bit 5 Bit 4 Thaw Cool Lock Filter 0 0 0 Chill 3 Bits 0 - 6, Fresh Food LED 0 Bits 0 - 6, Fresh Food LED 1 Bits 0 - 6, Fresh Food LED 2 Bits 0 - 6, Freezer LED 0	Bit 7 Bit 6 Bit 5 Bit 4 Bit 3 Thaw 1 Cool 1 Lock 5 Filter Door 1 0 0 Chill 3 2 Bits 0 - 6, Fresh Food LED 0 Bits 0 - 6, Fresh Food LED 1 Bits 0 - 6, Freezer LED 0 Bits 0 - 6, Freezer LED 1	Bit 7 Bit 6 Bit 5 Bit 4 Bit 3 Bit 2 Thaw Cool Lock Filter Door Cube 0 0 Chill Chill Chill 0 0 Chill 2 1 Bits 0 - 6, Fresh Food LED 0 Bits 0 - 6, Fresh Food LED 1 Bits 0 - 6, Freezer LED 0 Bits 0 - 6, Freezer LED 1	Bit 7 Bit 6 Bit 5 Bit 4 Bit 3 Bit 2 Bit 1 Thaw 1 Cool 1 Lock 5 Filter Door Cube Crush 1 Chill Chill Thaw 2 Thaw 3 0 0 Chill 2 Chill 3 Thaw 3 Bits 0 - 6, Fresh Food LED 0 Bits 0 - 6, Fresh Food LED 1 Bits 0 - 6, Freezer LED 0 Bits 0 - 6, Freezer LED 1	

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Lock	Reset	Fresh	Fresh	Freezer	Freezer	Defrost	Turbo
	Fresh	Food	Food	Dec	Inc	/ Chill	Cool
	Filter	Doc	Inc.				
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	0	Door	Thaw	Light	Cube	Water	Crush
					Key	Key	Key

Address	Com	Command	Communication	Dhysical Despense
Address	Com.	i i		Physical Response
	Byte	Received	Response	
0x12	0x01	Firmware Version	<3 byte ascii	
			version>	
0x12	0x6F	EEPROM data		
		from		
		mainboard		
0x12	0x90	Set Display		See table below
0x12	0x91	Read Buttons	<state of="" td="" various<=""><td></td></state>	
			Buttons -> 4 bytes >	
0x12	0x92	Pulse Beeper		
0x12	0xA4	Reply from main		
		with temperature		
		settings		
0x12	0xBA	Reply from main		
		with encoder		
		settings		
0x12	0xC0	Door Open		0x51 = door open
				0x41 = door closed
0x12	0xF2	Temperature to		
		main/dispenser		
		communications		
	<u></u>	test		
0x12	0xF3	Dispenser to main		· -
	-	communications		
		test		
0x12	0xF4	Open duct door		
0x12	0xF5	Sweat heater test		
0x12	0xF6	Sensor system self-		
		test		
0x12	0xF9	Forced reset		

Table 2	22							
Byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	Thaw 1	Cool	Lock	Filter	Door	Cube	Crush	Water
1	0	0	0	Chill 3	Chill 2	Chill 1	Thaw 3	Thaw 2
2	Bits 0 -	Bits 0 – 6, Fresh Food LED 0						

Byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
3	Bits 0 -	Bits 0 – 6, Fresh Food LED 1						
4	Bits 0 -	Bits 0 – 6, Fresh Food LED 2						
5	Bits 0 -	Bits 0 – 6, Freezer LED 0						
6	Bits 0 -	Bits 0 – 6, Freezer LED 1						
7	Bits 0 -	Bits 0 – 6, Freezer LED 2						

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Lock	Reset	Fresh	Fresh	Freezer	Freezer	Defrost	Turbo
	Fresh	Food	Food	Dec	Inc	/ Chill	Cool
	Filter	Dec	Inc.	1			
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	0	Door	Thaw	Light	Cube	Water	Crush
					Key	Key	Key

Table 25

	1 able 25						
Data Name	Length	Туре	Function				
(Module/Data)							
All Modules /	1	Char	R = Run				
State Code			I = Initialization				
Command	1	Structure Pointer	Points to String Where,				
Processor			Byte 1 = Command,				
/ Command			Byte 2 = Address,				
			Successive Bytes Data				
Command	1	Structure Pointer	Points to String Where,				
Processor			Byte 1 = Command,				
/ Command (Note:			Byte 2 = Address,				
for received			Successive Bytes Data				
commands)							
Dispense /	1	Unsigned Char	Bit 0 = Main Valve,				
Command			Bit 1 = Water Valve,				
			Bit 2 = Electromagnet,				
			Bit 3 = Auger,				
			Bit 4 = Crusher Sol.				
Protocol Data	1	Boolean	True Means Clear				
Parse	*	Boolean	Buffer				
/ Clr OK			False Means Do Not				
/ Cir Ok			Clear Buffer				
Protocol Data	1	Structure Pointer					
Parse	1	Structure Pointer	Points to String Where Boolean = Rstatus				
/ Command &							
			(True if command received				
Rstatus			and CS OK)				
			Byte 1 = Command				
			Byte 2 = Address				
			Successive Bytes Data				
Protocol Data	1	Boolean	True if last command				
XMIT			was successfully				
/ XMIT Status			transmitted.				
			False if last command				
			did not transmit or is				
			still transmitting.				
Protocol Data	1	String Pointer	Points to String Where				
XMIT			Byte 1 = Command				
/ Command			Byte 2 = Address				
			Successive Bytes Data.				
			NOTE: If pointer is				
,			NULL, then XMIT				
			Status is returned based				
			on the success or failure				
			of the previous				
			command.				
	L	-I-	1				

Data Name (Module/Data)	Length	Type	Function
LED Control / LED Pattern	1	Unsigned Long	Each of the 32 bits corresponds to an LED.
Keyboard Scan / Key Status & Key Value	1	Unsigned Int.	MSB = Key Status (1 = key pressed) Each of the bits beginning with the LSB correspond to a key. If no key is being pressed the contents of the status will reflect the last key combination pressed.
Protocol Packet Ready / Rstatus	1	Boolean	True if command received and CS OK Else it returns False
Physical Xmit Char / Char	1	Unsigned Char	Contains character to be transmitted
Physical Xmit Char / XMIT Status	1	Boolean	True if last command was successfully transmitted. False if last command did not transmit or is still transmitting.
XMIT Port Avail / xPort Status	1	Boolean	True if port is available. False if port is not available.
Key Pressed / Key Status	1	Boolean	True if key is pressed. False if key is not pressed.

Data Store Name	Size and Function
DayCount	4 Bytes – Counts Days for both Filter Functions
OneMinute	1 Byte – Set to 60 when initialized. At 0 one minute has passed.
RX Buffer	16 Bytes – Buffer used to store communication data
Turbo Timer	Unsigned Int – Contains the number of minutes remaining until Turbo Mode times out.
Chill Times	Unsigned Int – Contains the number of minutes remaining until Quick Chill Mode times out.
Daily Rollover	Unsigned Int - Counts minutes each day

Table 27

Name Length Type Function	
D = Diagnostic Col Data 1 Boolean True Means C Buffer	
Col Data 1 Boolean True Means C Buffer	on
Col Data 1 Boolean True Means C Buffer	cs
· · · · · · · · · · · · · · · · · · ·	
OK False Means D	
l l	Oo Not
Clear Buffer	
col Data 1 Structure Pointer Points to Strin	g Where
Boolean = Rst	_
nmand & (True if comm	and received
and CS OK)	
Byte 1 = Com	mand,
Byte $2 = Addr$, ,
Successive By	-
col Data 1 Boolean True if last con	
was successfu	
T Status transmitted.	
False if last co	mmand
did not transm	it or is
still transmitti	ng.
col Data 1 String Pointer Points to Strin	g Where
Byte 1 = Com	mand,
Successive By	
NOTE: If poir	nter is
NULL, then X	MIT
Status is return	ned based
on the success	or failure
of the previous	s
command.	
Calibration 1 Unsigned Char Sensor Number	er range 1 - 255
ants &	
rize / Sensor	
1120, 0011001	
	n degrees
Calibration 1 Signed Int Temperature in	
Calibration 1 Signed Int Temperature is ants & Fahrenheit Tir	nes 100
Calibration 1 Signed Int Temperature i	
Calibration 1 Signed Int Temperature in Fahrenheit Tir	
Calibration 1 Signed Int Temperature i Fahrenheit Tir Range – 12700	0 to
Calibration 1 Signed Int Temperature in Fahrenheit Tir Range – 12700 +12800	0 to
Calibration 1 Signed Int Temperature in Fahrenheit Time Range – 12700 + 12800 Sensor / 1 Unsigned Char Sensor Number	0 to er range 1 -
String Pointer Points to String Byte 1 = Communication Byte 2 = Addressive By NOTE: If point NULL, then X Status is return on the success of the previous command. Calibration 1 Unsigned Char Sensor Number	ig Where mand, ress, res Data. Inter is KMIT med based is or failure is cer range 1 - 25